



MATH1901 Differential Calculus (Advanced)

Chapter 3: Functions

Definitions

$$f : A \rightarrow B$$

- A and B are sets
- f assigns to each element x in A *exactly one* element in B
- A is the *domain* of the function
- B is the *codomain* of the function
- The *range* is the set of all possible values of $f(x)$ as x varies over the domain. It is a subset of the domain
- A vertical line should not cut the graph of a function more than once

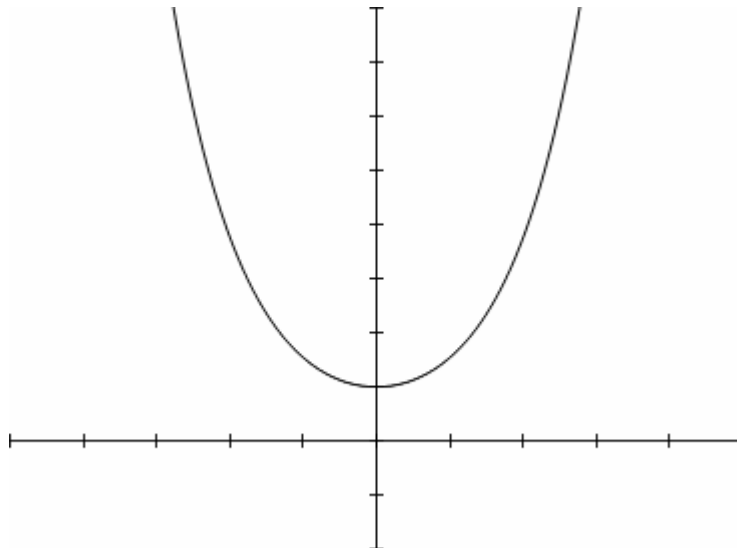
Composite Functions

$$(g \circ f)(x) = g(f(x))$$

for all x in the domain of f such that $f(x)$ is in the domain of g .

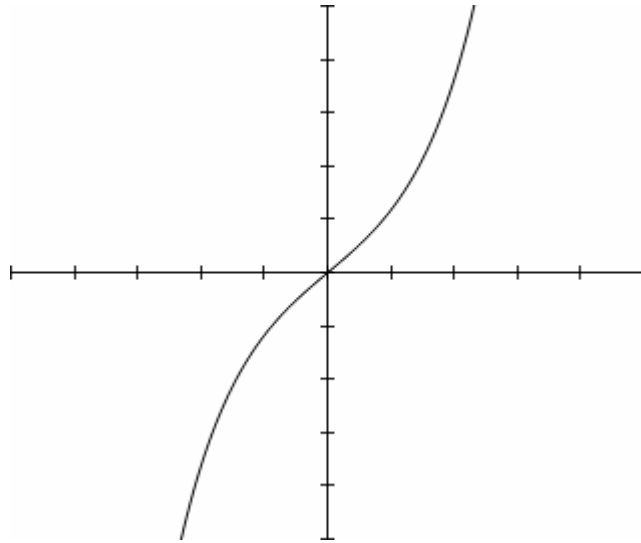
Hyperbolic Functions

$$\cosh x = \frac{e^x + e^{-x}}{2}$$





$$\sinh x = \frac{e^x - e^{-x}}{2}$$



Identities

- $\cosh^2 x - \sinh^2 x = 1$
- $\sinh(x + y) = \sinh x \cosh y + \cosh x \sinh y$
- $\cosh(x + y) = \sinh x \sinh y + \cosh x \cosh y$

Derivatives

- $\frac{d}{dx} \cosh x = \sinh x$
- $\frac{d}{dx} \sinh x = \cosh x$

Injective Functions

- A function is *injective* (or *one-to-one*) if distinct elements in its domain are mapped to distinct elements in its codomain.

Tests

- $x_1 \neq x_2 \Rightarrow f(x_1) \neq f(x_2)$ or $f(x_1) = f(x_2) \Rightarrow x_1 = x_2$
- The horizontal line test works if the function is from \mathbb{R} to \mathbb{R} .

Surjective Functions

- A function is *surjective* (or *onto*) if its range is equal to its codomain.



Bijjective Functions

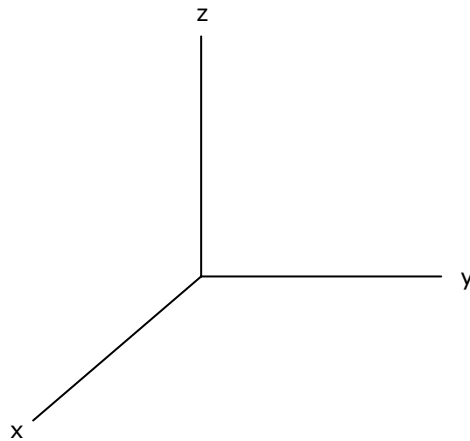
- A function is *bijjective* if it is both injective and surjective.

Inverse Functions

- Two functions $f : A \rightarrow B$ and $f^{-1} : B \rightarrow A$ are *inverse functions* if $(f^{-1} \circ f)(x) = x$ for all $x \in A$ and $(f \circ f^{-1})(x) = x$ for all $x \in B$
- A function has an inverse iff it is *bijjective*.

Chapter 4: Curves and Surfaces in 3-dimensional Space

Cartesian Coordinates in 3 Dimensions



Curves in 3-Dimensional Space

- A *single equation* that relates x , y and z will, in general, represent a surface.
- *More than one equation* is needed to represent a curve in three dimensions. This is done by parametric equations.

Planes

- The Cartesian equation of a plane in 3-dimensional space is of the form $ax + by + c = d$, where not all of a , b and c are zero.

Functions of Two Real Variables

- The *domain* is a region in \mathbb{R}^2 and the *codomain* is \mathbb{R} .
- The *range* is the set of all possible values taken by $f(x, y)$ as (x, y) varies over domain.



Chapter 5: Limits and the Limit Laws

Definition of a Limit

Intuitive Definition

- Suppose that l is a real number. The limit of $f(x)$ as x approaches c is equal to l , or $\lim_{x \rightarrow c} f(x) = l$, if we can make $f(x)$ as close as we like to l for all x sufficiently close to c (but not equal to c).

Mathematically Precise Definition

- Suppose that l is a real number. Then the limit of $f(x)$, as x approaches c , is equal to l if for any number $\epsilon > 0$ we can always find a number $\delta > 0$ such that $|f(x) - l| < \epsilon$ whenever $0 < |x - c| < \delta$.
- We first *choose* ϵ and then *find* a δ so that $|f(x) - l| < \epsilon$ whenever $0 < |x - c| < \delta$. Then that limit holds true if for every possible $\epsilon > 0$, we can always find such a δ .

The Squeeze Law

- A limit law: Suppose that $f(x) \leq g(x)$, for all x near c . Then $\lim_{x \rightarrow c} f(x) \leq \lim_{x \rightarrow c} g(x)$.
- The squeeze law: Suppose that $f(x) \leq g(x) \leq h(x)$, for all x near c , and that $\lim_{x \rightarrow c} f(x) = l$ and $\lim_{x \rightarrow c} h(x) = l$. Then $\lim_{x \rightarrow c} g(x) = l$.

Limits of Functions of Two Variables

Intuitive Definition

- $\lim_{(x,y) \rightarrow (c,d)} f(x,y) = l$ if we can make $f(x,y)$ as close as we like to l for all (x,y) sufficiently close to, but not equal to, (c,d) .

Mathematically Precise Definition

- Suppose that l is a real number. Then, the limit of $f(x,y)$, as (x,y) approaches (c,d) , is equal to l if for each $\epsilon > 0$ we can find a number $\delta > 0$ such that $|f(x,y) - l| < \epsilon$ whenever $0 < \sqrt{(x-c)^2 + (y-d)^2} < \delta$.
- The limit should exist and be the same no matter which direction you come from.

Limits at Infinity

- Suppose that l is a real number. Then, the limit of $f(x)$, as x approaches ∞ , is equal to l if for all $\epsilon > 0$ there exists an $N > 0$ such that $|f(x) - l| < \epsilon$ whenever $x > N$.
- The limit of $f(x)$, as x approaches $-\infty$, is equal to l if for all $\epsilon > 0$ there exists an $N > 0$ such that $|f(x) - l| < \epsilon$ whenever $x < -N$.



Infinite Limits

- The limit of $f(x)$, as x approaches c , is equal to ∞ if for every positive number $N > 0$, there exists a $\delta > 0$ such that $f(x) > N$ whenever $0 < |x - c| < \delta$.
- The limit of $f(x)$, as x approaches c , is equal to $-\infty$ if for every positive number $N > 0$, there exists a $\delta > 0$ such that $f(x) < -N$ whenever $0 < |x - c| < \delta$.
- The limit laws do *not* apply to infinite limits.

Chapter 6: Continuous Functions

Introduction

- Continuous functions do not make sudden jumps or changes.
- If f is a continuous function and if c belongs to the domain of f then $\lim_{x \rightarrow c} f(x) = f(c)$.

Continuity at a Point

- Suppose that $f(x)$ is a function and that c is a point in the domain of $f(x)$. Then $f(x)$ is continuous at $x = c$ if the limit $\lim_{x \rightarrow c} f(x)$ and is equal to $f(c)$.
- If $f(x)$ is continuous at $x = c$, then $f(c)$ is finite.

Ways in which a function can fail to be continuous at a point

- The function has a hole at the point
- It jumps
- There is an asymptote

Continuous Functions

- A function is *continuous* if it is continuous at every point in its domain. That is, $f(x)$ is continuous if $\lim_{x \rightarrow c} f(x) = f(c)$ for all c in the domain of f .
- A function is *continuous everywhere* if it is continuous for all real c .

Composition Law

- Suppose that $f(x)$ is a continuous function and that $\lim_{x \rightarrow c} g(x) = l$. Then

$$\lim_{x \rightarrow c} (f \circ g)(x) = f\left(\lim_{x \rightarrow c} g(x)\right) = f(l).$$



L'Hopital's Rule

- Suppose that $\lim_{x \rightarrow c} f(x) = 0$, $\lim_{x \rightarrow c} g(x) = 0$ and that the limit $\lim_{x \rightarrow c} \frac{f'(x)}{g'(x)}$ exists and is finite. Then $\lim_{x \rightarrow c} \frac{f(x)}{g(x)} = \lim_{x \rightarrow c} \frac{f'(x)}{g'(x)}$.
- Suppose that $\lim_{x \rightarrow c} f(x) = \pm\infty$, $\lim_{x \rightarrow c} g(x) = \pm\infty$ and that the limit $\lim_{x \rightarrow c} \frac{f'(x)}{g'(x)}$ exists and is finite. Then $\lim_{x \rightarrow c} \frac{f(x)}{g(x)} = \lim_{x \rightarrow c} \frac{f'(x)}{g'(x)}$.

The Intermediate Value Theorem

- Suppose that $f(x)$ is continuous on the closed interval $[a, b]$. Then $f(x)$ takes every value between $f(a)$ and $f(b)$ as x varies between a and b .
- Alternatively, if k is any number in between $f(a)$ and $f(b)$ then $f(x) = k$ has at least one solution in the interval $[a, b]$.
- The IVT can be applied to approximate the solution of an equation. Suppose that f is continuous on the interval $[a, b]$ and that $f(a)$ and $f(b)$ have different signs. Then $f(c) = 0$, for some $c \in [a, b]$.

Chapter 7: Differentiable Functions

The Derivative of a Function

- A function f is differentiable at $x = c$ if $f'(c) = \lim_{h \rightarrow 0} \frac{f(c+h) - f(c)}{h}$ exists.
- The derivative of a function f is $f'(x) = \lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$.

Differentiable Functions and Continuity

- Every differentiable function is continuous.

Functions can fail to be differentiable if

- The function is not differentiable at a point in the given interval, and has a sharp point or a cusp.
- The function changes too rapidly near a particular point.

Derivative of an Inverse Function

- Suppose that f is a differentiable function. Then f^{-1} is differentiable and

$$\frac{df^{-1}}{dx} = \frac{1}{f'(f^{-1}(x))}.$$



The Extreme Value Theorem

- Suppose that f is continuous on the closed interval $[a, b]$. Then f has both a minimum and a maximum value on $[a, b]$; that is, there exist numbers m and M such that $m \leq f(x) \leq M$, for all $x \in [a, b]$, $m = f(c)$ and $M = f(d)$ for some $c, d \in [a, b]$.
- The *range* of f on $[a, b]$ is $[m, M]$.
- A function f has a *local minimum* at $x = c$ if there exists a $\delta > 0$ such that $f(x) \geq f(c)$ for all $x \in (c - \delta, c + \delta)$. The same goes for *local maximum*.
- Suppose that f is differentiable on $[a, b]$ and that $c \in [a, b]$ is a maximum or a minimum value for f on $[a, b]$. Then either $c = a$, $c = b$ or $f'(c) = 0$.

The Mean Value Theorem

- Suppose that f is differentiable on $[a, b]$. Then there exists a number $c \in (a, b)$ such that $f'(c) = \frac{f(b) - f(a)}{b - a}$.

Chapter 8: Taylor Polynomials

Constructing Taylor Polynomials about $x = 0$

- The n th degree Taylor polynomial of a function f around $x = 0$ is

$$T_n(x) = f(0) + f'(0)x + \frac{f''(0)}{2!}x^2 + \frac{f'''(0)}{3!}x^3 + \dots + \frac{f^{(n)}(0)}{n!}x^n.$$

- The n th degree Taylor polynomial of a function f around $x = a$ is

$$T_n(x) = f(a) + f'(a)x + \frac{f''(a)}{2!}(x - a)^2 + \frac{f'''(a)}{3!}(x - a)^3 + \dots + \frac{f^{(n)}(a)}{n!}(x - a)^n.$$

The Remainder Term

- The difference between f and T_n is $R_n(x) = f(x) - T_n(x)$.
- The Lagrange form of the remainder is $R_n(x) = \frac{f^{(n+1)}(c)}{(n+1)!}x^{n+1}$.

Chapter 10: Partial Derivatives and Tangent Planes

- Let f be a function of two variables. Then the partial derivative of f with respect to x is

$$\frac{\partial f}{\partial x} = f_x(x, y) = \lim_{h \rightarrow 0} \left(\frac{f(x+h, y) - f(x, y)}{h} \right).$$

- Let f be a function of two variables. Then the partial derivative of f with respect to y is

$$\frac{\partial f}{\partial y} = f_y(x, y) = \lim_{h \rightarrow 0} \left(\frac{f(x, y+h) - f(x, y)}{h} \right).$$



- If (a, b) belongs to the domain of f , f_x and f_y exist and are continuous when $x = a$ and $y = b$ then f is differentiable at (a, b) .

Higher Order Partial Derivatives

- $(f_x(x, y))_x = f_{xx}(x, y) = \frac{\partial^2 f}{\partial x^2}$
- $(f_x(x, y))_y = f_{xy}(x, y) = \frac{\partial^2 f}{\partial y \partial x}$
- $(f_y(x, y))_x = f_{yx}(x, y) = \frac{\partial^2 f}{\partial x \partial y}$
- $(f_y(x, y))_y = f_{yy}(x, y) = \frac{\partial^2 f}{\partial y^2}$

Tangent Planes

- The equation of the tangent plane is $z - f(a, b) = f_x(a, b)(x - a) + f_y(a, b)(y - b)$.

Linear Approximation Using Differentials

- The differential of a function of two variables is given by $dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy$.

The Total Derivative Rule

- Suppose that $z = f(x, y)$ where $x = g(t)$ and $y = h(t)$ and f , g and h are all differentiable functions. Then the total derivative of z is given by $\frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt}$.

Implicit Differentiation

- $\frac{dy}{dx} = \frac{-f_x(x, y)}{f_y(x, y)}$

Chapter 12: Directional Derivatives and the Gradient Vector

The Gradient Vector and the Directional Derivative

- The gradient of f is $\text{grad } f(x, y) = \nabla f(x, y) = \frac{\partial f}{\partial x} \mathbf{i} + \frac{\partial f}{\partial y} \mathbf{j}$.
- The directional derivative of f in the direction of a unit vector u is
$$D_u f(x, y) = \mathbf{u} \cdot \nabla f(x, y) = u_1 f_x(x, y) + u_2 f_y(x, y)$$
$$= \lim_{h \rightarrow 0} \frac{f(a + hu_1, b + hu_2) - f(x, y)}{h}$$



Interpreting the Gradient Vector

- $D_u f(a, b) = |\nabla f(a, b)| \cos \theta$ where θ is the angle between ∇f and \mathbf{u}
- Hence the greatest value of the directional derivative is $|\nabla f(a, b)|$. The direction of steepest increase of $f(x, y)$ is ∇f .
- It will take its largest negative value when u is in the opposite direction to ∇f .
- The tangent with zero slope lies in the direction at right angles to the gradient vector.
- ∇f is normal to the level curve $f(x, y) = c$.